

Experimental Study on a Buffered Tuned-Mass Damper of Offshore against Earthquake Vibration

Qiong Wu^{1,a} Xilu Zhao^{1,b}

¹College of Mechanical Engineering Saitama Institute of Technology, Saitama 369-0293, Japan

^a< wuqiong55@126.com >, ^b<zhaoxilu@sit.ac.jp>

Keywords: Buffered tuned-mass damper, Offshore platform, Experimental study, Earthquake vibration reduction.

Abstract. This paper investigates the buffered tuned-mass damper (TMD) for an offshore structure. The purpose of this paper is to find an effective and economic means to reduce the wave induced vibrations of the offshore platform system. This paper proposes a bufferable TMD, a passive TMD with buffers on both sides, to improve the performance of offshore platforms subjected to large seismic waves. A comprehensive experiment was executed to investigate the dynamic performances of the bufferable TMD, by application of a 1:200-scale offshore platform prototype. It is verified that the bufferable TMD can be effective in absorbing the vibration energy. In conclusion, the experimental results indicate that the response of an offshore platform can be significantly decreased, and the evaluation indices show that the method is effective in reducing overall vibration levels and maximum peak values, with the application of the bufferable damper system.

1. Introduction

Normally, offshore platform, located in the hostile environment, is easily subjected to unstable environmental loading, such as wind, wave, ice, and earthquake, and it becomes a critical problem to ensure the stability of offshore platform for safely engineering operations, offshore jacket platform plays an indispensable role in the development and utilization of marine resources [1]. Located in hostile ocean environments, offshore platforms are exposed to external disturbances such as winds and earthquakes, which generally lead to large oscillation of the system [2].

While many efforts have been put in the study of the platform and waves, rare attention is being paid on the vibration mitigation. There are two intractable problems while taking into account the possibility of damage to the offshore platform during a high intensity earthquake. One such problem is that the large earthquake excitation may cause local damage to the vibration absorber; and another problem is that the duration of an earthquake excitation event is generally short.

To solve the problem of stroke between vibration absorber and target structure, several attempts had been made to decrease the stroke, by introducing the idea of impact dampers. An impact damper is a freely moving mass, constrained by stops fixed to a dynamically excited structure to be controlled. Energy is dissipated as heat and noise together with the development of high frequency vibrations in the structure [3]. On the other hand, the impact dampers will produce impulsive loads between the two coupled systems, and will cause a high-level noise during the impact process. In contrast, buffer materials have been incorporated in the impact damper system to reduce impact forces [4]. Chen et al. [5] performed numerical modeling of impact damping with a discrete element method, and it indicated that the collision and friction mechanism might play different or equivalent roles in energy dissipation, under different vibration and particle system parameters. As to the fundamental theory of impact dampers, numerical and experimental studies had been undertaken to test specific applications, check theoretical results, and select parameters of impact damper systems [6–9]. Li [10] and Liu et al. [11] conducted a series of experimental investigations to examine the effect of an impact damper, using equivalent viscous damping model to represent the nonlinearity. Damping characteristics of an impact damper were also studied to improve the damping capability.

Fang and Tang [12] developed an improved analytical model using multiphase flow theory based on the previous work of Wu et al. [13]. Recently, experimental work has studied the effect of controlling friction-driven oscillations using an impact damper, and the effects of mass ratio, coefficient of restitution, and clearance on the performance of an impact damper was verified through the experimental and numerical investigations [14].

For an earthquake excitation in which its duration is substantially shorter, considerable disasters often occurred during the initial period of an earthquake load. The several previous studies [15-17] used the vibration absorber with viscous damping to improve the vibration control effectiveness; however, because the high response performance of the dampers is not considered, the dampers may not have enough reaction time to produce a significant effect in the initial seconds of the earthquake excitation.

This paper involves experimental and analytical investigations that comprehensively extend the understanding of the high response performance and damping characteristics of bufferable TMD systems under two large seismic vibrations. The experimental processes were based on a prototype of an existing offshore jacket platform, and the bufferable, high-response, absorption characteristics were discussed dependent on the results of the amplitude and frequency responses.

2. Methods

2.1. Description

This study makes use of a TMD with a buffer to realize the advantages of both the TMD with and without damper. The TMD device (Figure 1) consists of a frame, a mass, two springs, four wheels, two tracks, and two buffers. The buffers, which adopt buffering materials, can be fixed to the frame by adhesive. The gap between the buffer and mass can be adjusted depending on performance.

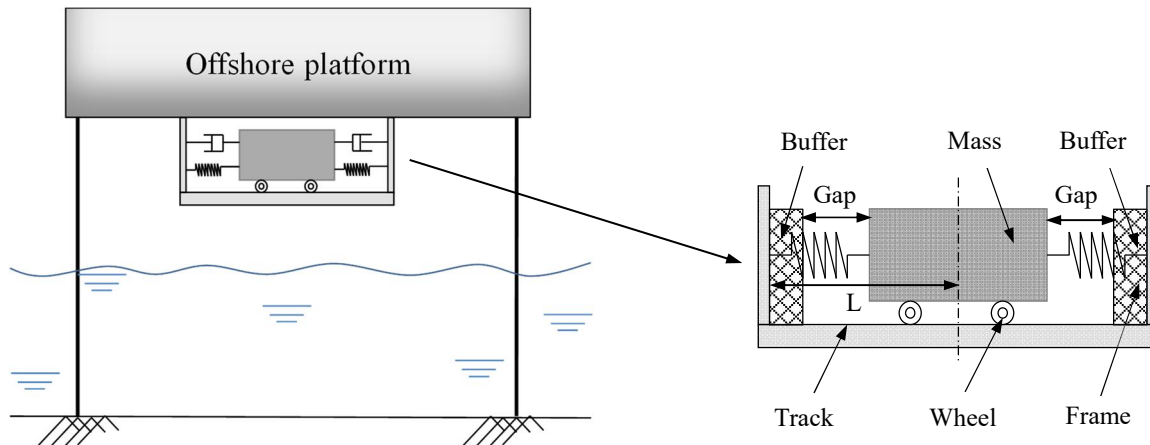


Fig.1. Schematic of a jack-up offshore platform with a bufferable TMD

3. Evaluation Parameters

A root mean square (RMS) of the displacement or acceleration response can be expressed as

$$RMS = \sqrt{\frac{1}{n} \sum_{i=1}^n y_i^2} \quad , \quad (1)$$

where y_i is the sampling value of the displacement or acceleration responses. To evaluate effectiveness of the vibration reduction during the entire earthquake period, an evaluation parameter index was proposed:

$$J = \frac{RMS_{ctrl}}{RMS_{unctrl}}, \quad (2)$$

where RMS_{ctrl} and RMS_{unctrl} are the RMS values of the displacement or acceleration responses of the main structure for the entire earthquake period, for the cases with and without the TMD system, respectively. To evaluate the maximum response reduction, a maximum peak value was selected as $y_{max} = \max\{y_i\}$. Then, a relative ratio of the maximum peak values can be obtained from

$$\beta = \frac{y_{max-unctrl} - y_{max-ctrl}}{y_{max-unctrl}}, \quad (3)$$

where $y_{max-ctrl}$ and $y_{max-unctrl}$ are the maximum peak values of the displacement or acceleration response of the main structure with and without the TMD system, respectively.

4. Experiment

4.1. Setup

As shown in Figure 2, the testing system comprised a computer, vibration signal generator, amplifier, shaker, offshore platform system, acceleration sensor, laser displacement sensor, and fast Fourier transform analyzer. The Bohai No. 5 offshore jack-up platform, located in the Southern Sea, was used as a research target to analyze the practical effectiveness of a TMD. A 1:200-scale model of the actual four-column platform was constructed. The size of the working platform is $57.5 \times 34.0 \times 5.50$ m, with operating leg lengths of 78 m and diameters of 3 m. The minimum operating water depth is 4 m.

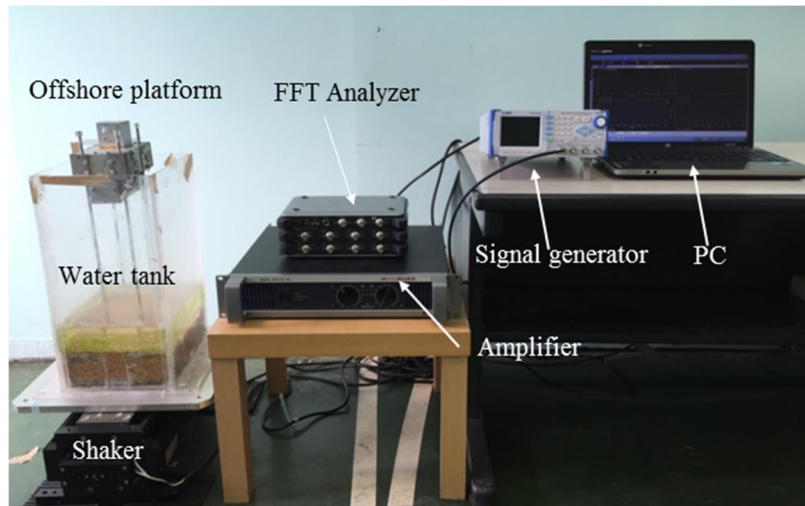


Fig. 2. Diagram of the experimental system

The modeled operating platform was scaled and simplified into a horizontal rectangular metal mass with support columns constructed of hollow tubes. Cylindrical pile shoes were set at the base of each column and the connections between the columns and the operating platform were rigid. The model platform was placed in a tank that was fixed to the shaker apparatus capable of simulating seismic loads. The response of the structure was measured using an accelerometer and a laser vibrometer. In the experiment, the sand height was 80 mm, and the water depth was 400 mm. The

mass of the main structure of the model platform (m_1) was 2.346 kg and the mass of the bufferable TMD was 0.591 kg. Through experimental validation, the damping coefficient of the offshore platform was determined to be 0.012, with a buffer damping coefficient of 0.012.

5. Results

5.1 Amplitude Responses

As presented in Fig 4 and Fig.5, the time series of the responses are shown for the main structure with and without the bufferable TMD under the excitations of the Fukujima NS and Taft EW seismic waves. The experimental results show that the peak values of the displacement responses decreased significantly with bufferable TMD control, when compared with those cases without bufferable TMD control. It can be observed that this decreasing tendency was more significant for the acceleration responses. These results indicate that the control performance of the bufferable TMD is effective as an energy-dissipation device for the reduction of the main structural response.

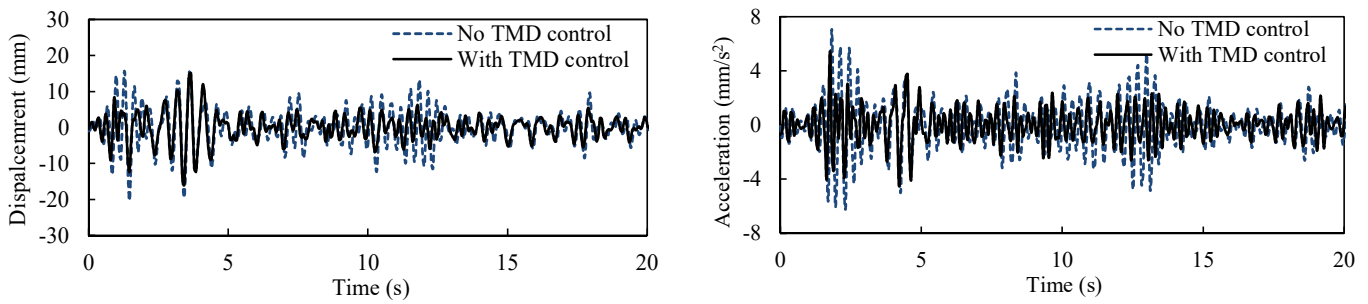


Fig. 4. Experimental results of the amplitude responses under the Fukujima NS seismic waves.

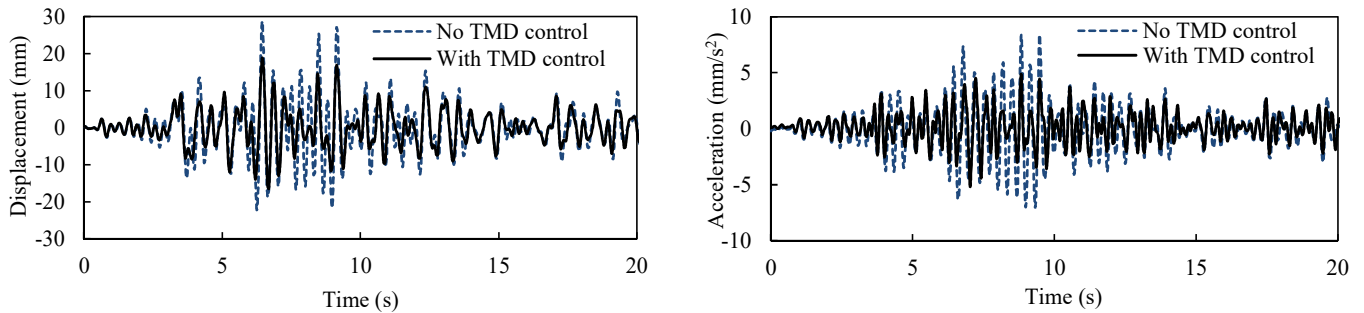


Fig. 5. Experimental results of the amplitude responses under the Taft EW seismic waves.

5.2 Frequency Responses

The power spectral density (PSD) results are presented in Figure 6 and Figure 7 for the displacement and acceleration of the platform with and without the bufferable TMD. The maximum amplitude of the PSD is observed to occur at around 3 Hz for the case without bufferable TMD control; the resonance reaction of the platform is seen to occur around this frequency. This explains why the designed bufferable TMD's frequency was nearly 3 Hz. The overall vibration response can be decreased significantly by reducing first-mode vibrations, and the resulting PSD curves explain why the time series response is effective for vibration reduction. Consequently, a single damper tuned to the fundamental mode is adequate for reducing structural vibrations resulting from

earthquake excitations. Investigations of frequency bands above or below the fundamental frequency revealed no negative effects at non-dominant frequencies.

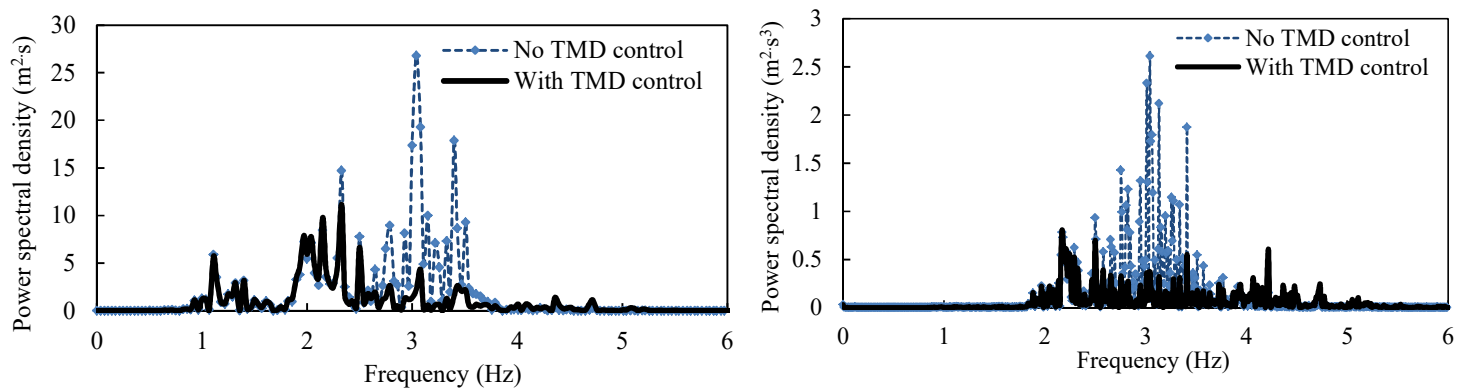


Fig. 6. Experimental results of the frequency responses under the Fukujima NS seismic waves.

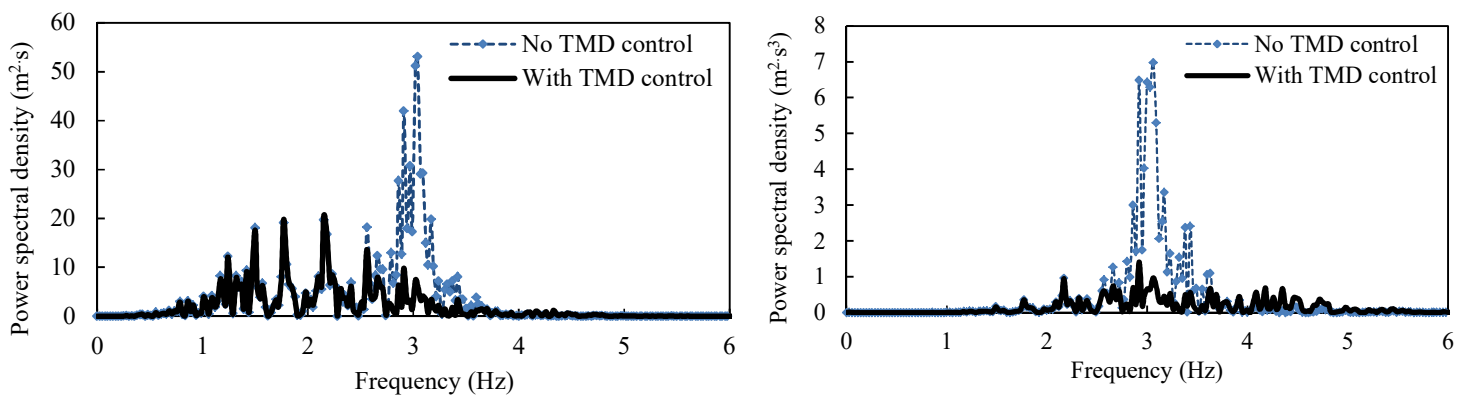


Fig. 7. Experimental results of the frequency responses under the Taft EW seismic waves.

6. Evaluation Index

Two performance indices are employed as shown in Table 1. The J values for the displacement response are more than 65.5%, which indicates that the vibration of the platform was significantly improved during the period of earthquake excitation when the bufferable TMD was used. Moreover, analysis of the β values shows that a reduction more than 34.5% was accomplished for the peak displacement response, by applying the bufferable TMD system. For the acceleration displacement response, the J values are more than 70%, which means that the dynamic performance was considerably improved throughout the entire period of the earthquake. Over the same time, the β values are more than 23.8%, which means that the peak response was also decreased by the application of the bufferable TMD system.

Table 1 Results of the evaluation indices

Seismic excitation	Displacement response		Acceleration response	
	ρ	J	ρ	J
Fukushima NS	0.422	0.746	0.238	0.784
Taft EW	0.345	0.731	0.479	0.655

7. Conclusions

This study proposes a bufferable TMD system to mitigate damaging responses of an offshore platform exposed to significant earthquake-sourced seismic waves. Moreover, a comprehensively numerical and experimental investigation has been conducted to examine bufferable high-response absorption processes. The preliminary results indicated that the displacement, acceleration and frequency performances of the offshore platform were significantly improved under two types of earthquake-induced seismic loads.

In conclusion, the experimental investigations verify that the bufferable TMD constitutes a simple but feasible measure against stroke for vibration suppression under large earthquake loads.

References

- [1] B. L. Zhang and Q. L. Han, "Network-based modelling and active control for offshore steel jacket platform with TMD mechanisms," *Journal of Sound and Vibration*, vol. 33, no. 25, pp. 6796–6814, 2014.
- [2] B. L. Zhang, L. Ma, and Q. L. Han, "Sliding mode H_∞ control for offshore steel jacket platforms subject to nonlinear self-excited wave force and external disturbance" *Nonlinear Analysis: Real World Applications*, vol. 14, no. 1, pp. 163–178, 2013.
- [3] K. Li and A. P. Darby, "An experimental investigation into the use of a buffered impact damper," *Journal of Sound and Vibration*, vol. 291, no. 3–5, pp. 844–860, 2006.
- [4] K. Li and A. P. Darby, "A buffered impact damper for multi-degree-of-freedom structural control," *Earthquake Engineering & Structural Dynamics*, vol. 37, no. 13, pp. 1491–1510, 2008.
- [5] T. Chen, K. Mao, X. Huang, and M. Wang, "Dissipation mechanisms of non-obstructive particle damping using discrete element method," *Proceedings of SPIE International Symposium on Smart Structures and Materials*, vol. 4331, no. 4, pp. 294–301, 2001.
- [6] S. E. Osire and I. C. Desen, "Experimental study on an impact vibration absorber," *Journal of Vibration and Control*, vol. 7, no. 4, pp. 475–493, 2001.
- [7] M. D. Thomas, W. A. Knight, and M. M. Sedek, "The impact damper as a method of improving cantilever boring bars," *Journal of Engineering Industry, ASME*, vol. 97, no. 3, pp. 859–866, 1975.
- [8] S. Ema and E. Marui, "Fundamental study on impact dampers," *International Journal of Machine Tools and Manufacture*, vol. 34, no. 3, pp. 407–421, 1994.
- [9] M. Y. Yang, G. A. Lesieutre, S. A. Hambric, and G. H. Koopmann, "Development of a design curve for particle impact dampers," *Noise Control Engineering Journal*, vol. 53, no. 1, pp. 5–13, 2005.
- [10] K. Li and A. P. Darby, "Experiments on the effect of an impact damper on a multiple-degree-of-freedom system," *Journal of Vibration and Control*, vol. 53, no. 1, pp. 5–13, 2005.
- [11] W. Liu, G. R. Tomlinson, and J. A. Rongong, "The dynamic characterisation of disk geometry particle dampers," *Journal of Sound and Vibration*, vol. 280, no. 3–5, pp. 849–861, 2005.
- [12] X. Fang and J. Tang, "Granular damping in forced vibration: qualitative and quantitative analyses," *Journal of Vibration and Acoustics*, vol. 128, no. 4, pp. 489–500, 2006.
- [13] C. Wu, W. Liao, and M. Y. Wang, "Modeling of granular particle damping using multiphase flow theory of gas-particle," *Journal of Vibration and Acoustics*, vol. 126, no. 2, pp. 196–201, 2004.
- [14] P. B. Zinjade and A. K. Mallik, "Impact damper for controlling friction-driven oscillations," *Journal of Sound and Vibration*, vol. 306, no. 1–2, pp. 238–251, 2007.
- [15] T. Pinkaew, P. Lukkunaprasit, and P. Chatupote, "Seismic effectiveness of tuned mass dampers for damage reduction of structures," *Engineering Structures*, vol. 25, no. 1, pp. 39–46, 2003.
- [16] A. Ghosh and B. Basu, "Effect of soil interaction on the performance of tuned mass dampers for seismic applications," *Journal of Sound and Vibration*, vol. 274, no. 3–5, pp. 1079–1090, 2004.
- [17] C. Lin, J. Ueng, and T. Huang, "Seismic response reduction of irregular buildings using passive tuned mass dampers," *Engineering Structures*, vol. 22, pp. 513–524, 2000.